HW9 deadline: 2020/05/12

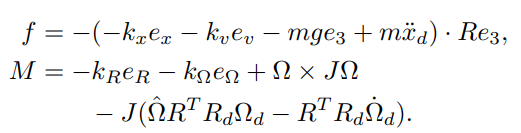
Please find the attached for the Simulink model for the UAV.

Given ,*d* =.

*R* is initially aligned with ..

The homework is to design a geometric controller with **attitude controlled flight mode**.

Hint:

1. You need to modify “**controller.m**”
2. There is explanation for every function in “**readme.txt**”
3. Don’t implement this term.
4. You must show in **scope** of Simulink.